

#### The Campus Chronicles: Where Science Meets Superheroes

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### JY OF P GINEERING

Teminian Seilkhan and Abylai Biahmetov



After all, you graduated from high school, what faculty are you going to enter?

On 29th of August, in 1962, the

Physics and Engineering was

opening of the Faculty of



For now I have no idea where to study, do you have any suggestions?



Luckily,

Once upon a time on the territory of TSU

I have a great idea. I can tell you about the faculty where I studied.

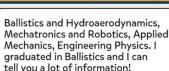


By 1968, a team of scientists, numbering about 80 people and 5 specialties, had formed at the faculty.

And what were the specialties originally?

It was Ballistics, Flight Dynamics, Aeromechanics and Thermodynamics, Control, Computational Mathematics.

what specialties are left at the moment?







tell you a lot of information!



The Flight Dynamics department was one of the first at the faculty. And it was headed by Valentin P. Stepanov. Now the head of the department is Vladimir I. Bimatov, whom you may choose as your academic supervisor!



This is all interesting, of course, but what can you do at the faculty in general?

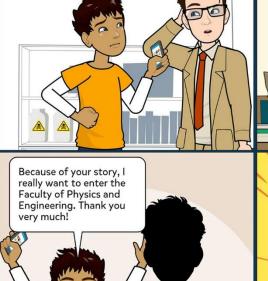


You can do a lot of things at our faculty, except studies! You can devote yourself both to scientific activity and to the active life of the university, participating in all sorts of events! And if you are doing public affairs, sports, creativity and science, you are entitled to a good scholarship.













Abylai eventually entered the Faculty of Physics and Engineering and did not regret his choice!



A few months later...



### OCCASION

Alyona Litvinova, Danila Borzikov, Albert Iksanov









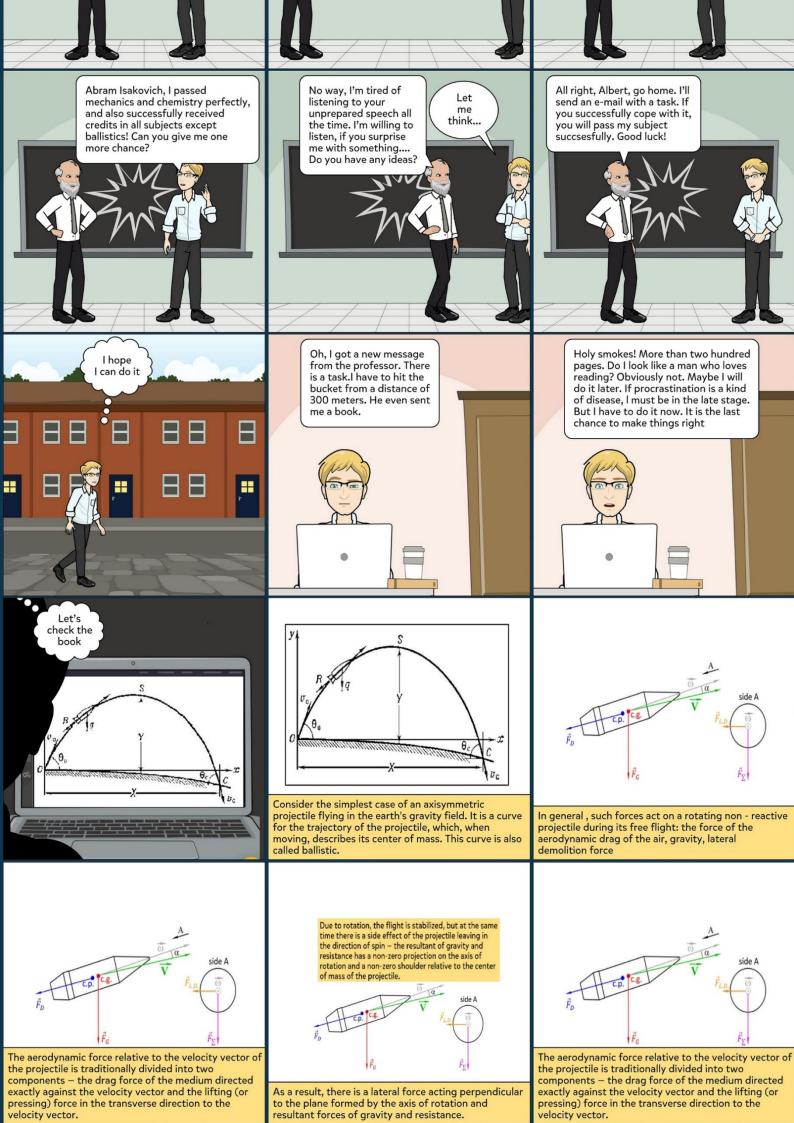
You've listened, but you haven't heard me. It is your fourth try. It's time to remember that the results are known immediately!

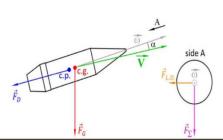
Oh, excuse me, I completely forgot. Can I retake the exam again ... for the fifth time? What day can I come up?



Ha! You must be joking, stop fooling me and yourself. A commission will be assembled, which will determine your future fate.

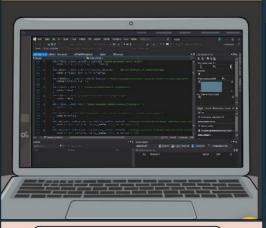






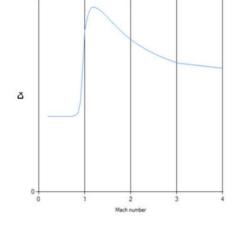
The last component can't affect on the flight of the projectile and in practice it can be neglected. The point of application of this force to the projectile is the center of pressure, which usually does not coincide with the center of mass. The position of the center of pressure depends on the shape of the projectile only.

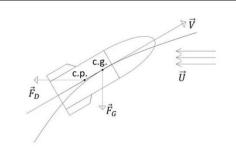
For me to solve this problem, I have to write a program that will solve a system of differential equations using some numerical method.



We will recalculate the values of the desired parameters every 0.001 seconds. It is important to remember that with the change in altitude, the parameters of the atmosphere also change, so their values will be recalculated at each step

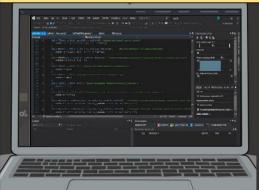






In a simplified case, it can be assumed that only two forces act on a non-rotating projectile without reactive thrust: The force of resistance directed against the speed of movement. Its value is proportional to the characteristic cross-sectional area, the density of the medium and the square of the velocity, Cx is a dimensionless aerodynamic drag coefficient and gravity.

I think that the Runge-Kutta method of the 5th order of accuracy is the most suitable for solving this system, since it provides high accuracy with a relatively small number of calculations, and it is not difficult to choose the optimal step automatically for it.



 $\begin{cases} T = 288.15 - 0.00650 \cdot h \text{ K}, & 0 \text{ } m \leq h < 11000 \text{ } m \\ T = 216.66 \text{ K}, & 11000 \text{ } m \leq h < 25000 \text{ } m \end{cases}$  $q = q_0 \cdot (1 - 2.256 \cdot 10^{-5}h)^{4.256} \frac{kg}{-3}$  $0 \ m \le h < 11000 \ m$  $q = q_0 \cdot 0.29784e^{-\frac{h-11000}{6342}} \frac{kg}{2}$  $11000 \ m \leq h < 25000 \ m$ 

We will recalculate temperature, air density, speed of

$$M_{\rm rm} = \begin{cases} 1.17 \cdot 10^{-3}, & v < 275 \, m/z \\ 1.17 \cdot 10^{-3} + (v - 275) \cdot \left( (1.34 - 1.17) \cdot \frac{10^{-3}}{25} \right), & 275 \, m/z < v \le 300 \, m/z \\ 1.34 \cdot 10^{-2} + (v - 300) \cdot \left( (1.37 - 1.34) \cdot \frac{10^{-2}}{25} \right), & 300 \, m/z < v \le 325 \, m/z \\ 1.37 \cdot 10^{-3} + (v - 325) \cdot \left( (1.36 - 1.37) \cdot \frac{10^{-3}}{25} \right), & 325 \, m/z < v \le 350 \, m/z \\ 1.36 \cdot 10^{-3} + (v - 350) \cdot \left( (1.32 - 1.36) \cdot \frac{10^{-3}}{25} \right), & 350 \, m/z < v \le 375 \, m/z \\ 1.32 \cdot 10^{-2} + (v - 375) \cdot \left( (1.28 - 1.32) \cdot \frac{10^{-3}}{25} \right), & 375 \, m/z < v \le 400 \, m/z \\ 1.28 \cdot 10^{-3} + (v - 400) \cdot \left( (1.21 - 1.28) \cdot \frac{10^{-3}}{50} \right), & 450 \, m/z < v \le 500 \, m/z \\ 1.21 \cdot 10^{-3} + (v - 450) \cdot \left( (1.16 - 1.21) \cdot \frac{10^{-3}}{50} \right), & 500 \, m/z < v \le 600 \, m/z \end{cases}$$

After starting, the program outputs the received data at each point through the selected step, so we get the values: projectile velocity; the angle of inclination of the tangent

trajectory to the horizon: course angle:

I used a system of differential equations describing how the parameters of the projectile motion change during its free flight. You can equations and programm panel in comments!

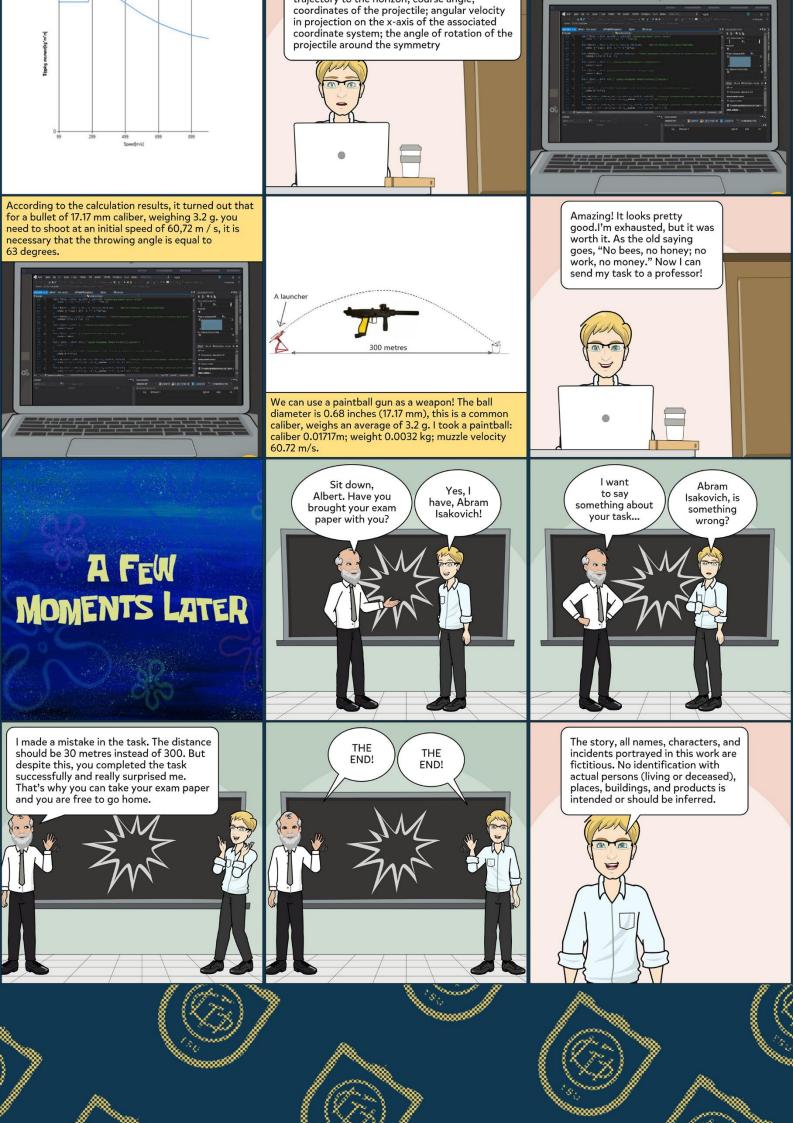
$$\begin{split} X_{k+1} &= X_k + \frac{1}{6}(k_1 + 2k_2 + 2k_3 + k_4)\,, \\ Y_{k+1} &= Y_k + \frac{1}{6}(m_1 + 2m_2 + 2m_3 + m_4)\,, \ldots, \\ \text{где} \\ k_1 &= f(t_k, X_k, Y_k, \ldots) \Delta t\,, \\ m_1 &= g(t_k, X_k, Y_k, \ldots) \Delta t\,, \ldots, \\ k_2 &= f(t_k + \frac{\Delta t}{2}, X_k + \frac{k_1}{2}, Y_k + \frac{m_1}{2}, \ldots) \Delta t\,, \\ m_2 &= g(t_k + \frac{\Delta t}{2}, X_k + \frac{k_1}{2}, Y_k + \frac{m_1}{2}, \ldots) \Delta t\,, \ldots, \\ k_3 &= f(t_k + \frac{\Delta t}{2}, X_k + \frac{k_2}{2}, Y_k + \frac{m_2}{2}, \ldots) \Delta t\,, \ldots, \\ m_3 &= g(t_k + \frac{\Delta t}{2}, X_k + \frac{k_2}{2}, Y_k + \frac{m_2}{2}, \ldots) \Delta t\,, \ldots, \\ k_4 &= f(t_k + \Delta t, X_k + k_3, Y_k + m_3, \ldots) \Delta t\,, \ldots, \\ m_4 &= g(t_k + \Delta t, X_k + k_3, Y_k + m_3, \ldots) \Delta t\,, \ldots \end{split}$$

It is also necessary to recalculate the speed of sound, the Mach number and the aerodynamic coefficient of air resistance, according to the written formulas:

$$Cx = \begin{cases} 0.0301 - 0.011M, & 3.06 < M \le 3.53 \\ 0.29(M)^{-1} + 0.172, & 1.62 < M \le 3.06 \\ 0.384 \sin{(1.85(M)^{-1})}, & 1.18 < M \le 1.62 \\ 0.384 - 1.6(M - 1.176)^2, & 1 < M \le 1.18 \\ 1.5M - 1.176, & 0.91 < M \le 1 \\ 0.161 + 3.9(M - 0.823)^2, & 0.82 < M \le 0.91 \\ 0.033M + 0.133, & 0.73 < M \le 0.82 \\ 0.157, & M < 0.73 \end{cases}$$

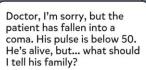
 $1.06 \cdot 10^{-9} + (v - 600) \cdot \left( (0.98 - 1.06) \cdot \frac{10^{-9}}{100} \right)$  $0.98 \cdot 10^{-8} + (v - 700) \cdot \left( (0.92 - 0.98) \cdot \frac{10^{-8}}{100} \right)$  $0.82 \cdot 10^{-8} + (v - 1100) \cdot \left( (0.81 - 0.82) \cdot \frac{10^{-8}}{100} \right)$ .  $1100 \text{ m/s} < v \le 1200 \text{m/s}$  $0.81 \cdot 10^{-3} + (v - 1200) \cdot \left( (0.80 - 0.81) \cdot \frac{10^{-2}}{100} \right), \quad 1200 \text{ m/s} < v \le 1280 \text{ m/s}$ 

To calculate the necessary parameters for our task, we will enter the calculation completion parameter when the x coordinate reached is 300 m and the height is zero. We will shoot in the absence of wind. We will select the necessary values of angle of inclination.



## QUANTUM THEOR Sergey Bogdanov, Ivan Polyakov

Voiced version:https://drive.google.com/file/d/1yZPArij-CVY73yxHDfXL3q2VtIUqtAm6/view





Don't worry, Kate. Unfortunately, my fears have come true. The operation was very complicated and therefore too long.



I was sure I could handle it. Apparently I overestimated my abilities. I shouldn't have agreed to this operation...



You're going to be suspended from your job now,



Yes, unfortunately I will be suspended from work until the trial. And now I need to meet with his family and inform them about the failed operation.



One of the most difficult moments in the work of a doctor is a conversation with the patient's family.



Mom, look, our doctor is coming!



Hello. I should ask for your attention. I'm Dr. Gibbs.



As a result of the 13-hour surgical operation, complications appeared. To put it another way, the young man fell into a deep coma. Now his life is not in danger. He is stable.

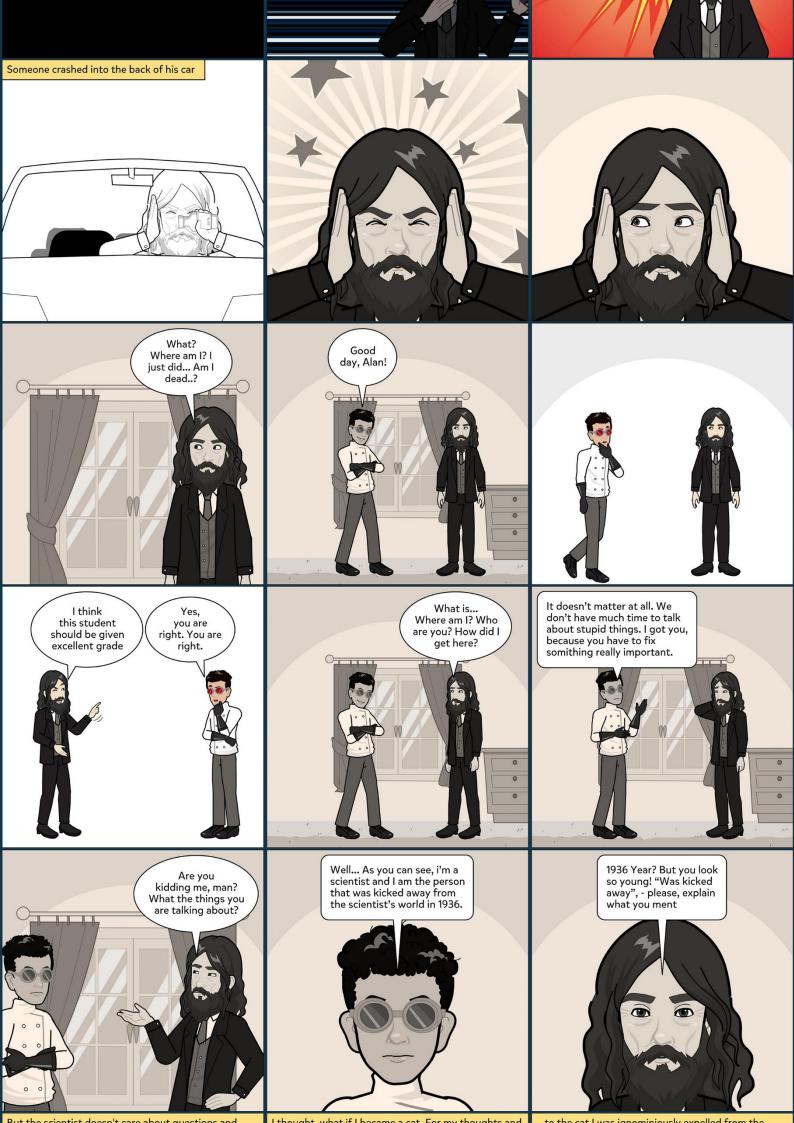


But he said that everything would be fine...

You promised us that you would handle this operation! How could you let this happen! What kind of doctor you are?! I will ensure that your medical license is taken away













Schrödinger's cat: a cat, a flask of poison, and a radioactive source are placed in a sealed box.



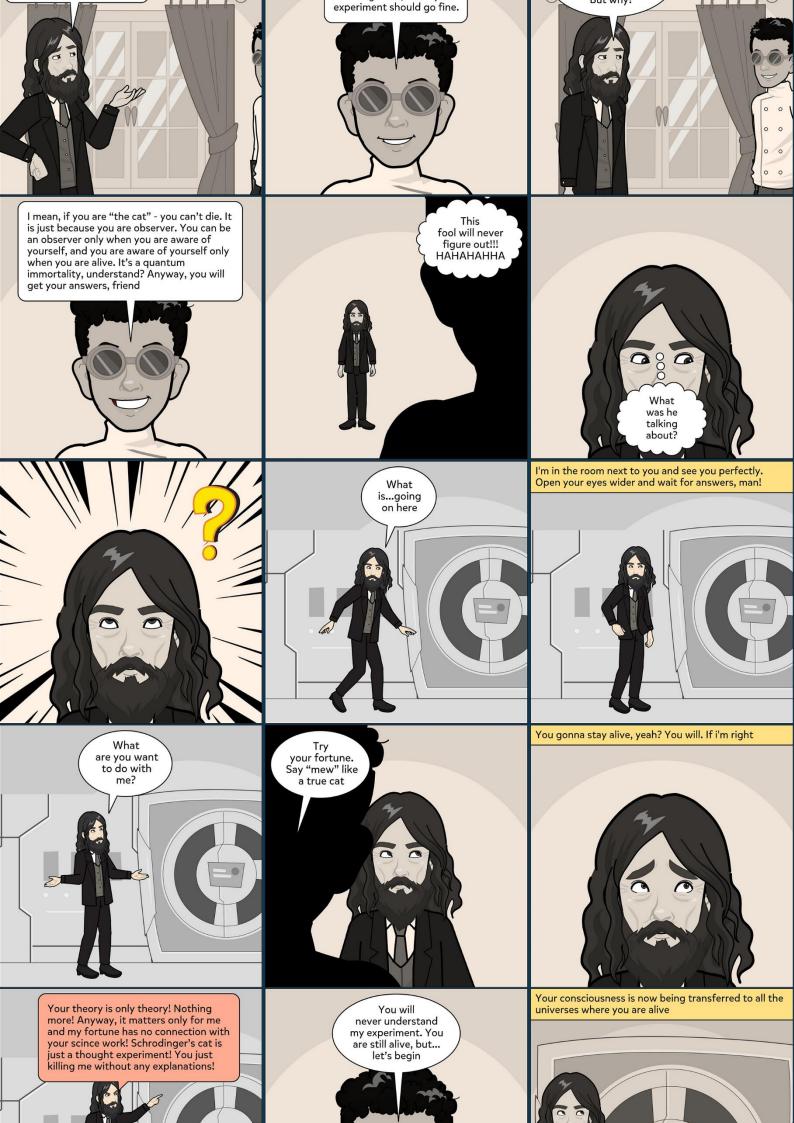
But the scientist didn't listen the doctor's questions

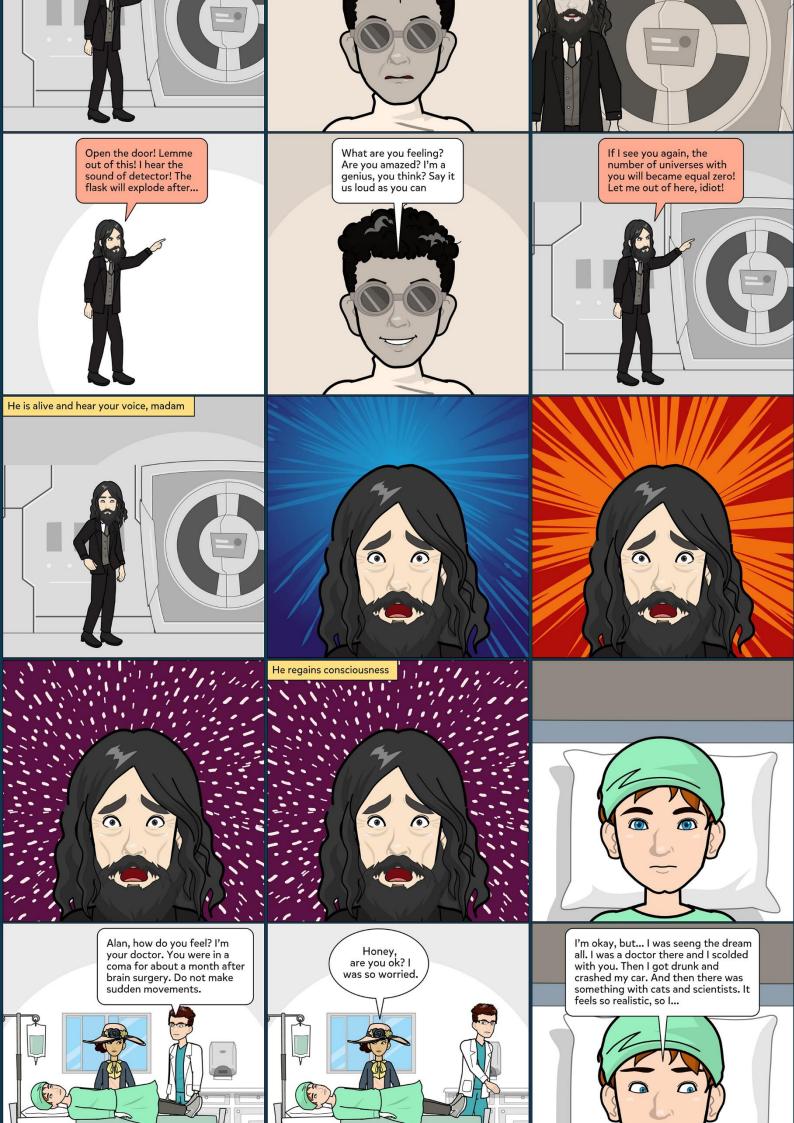
Then I decided to put myself in the cat's place. It's dangerous, but my



Are you suggesting to play Russian roulette? I've heard it's funny... But why?

what does that have to do with it? I've heard about it, but I don't understand how I'm connected with it?



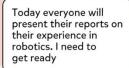






## ME IN ROBOTICS

Alina Martynova





I started learning how to solder and model in CAD systems such as Fusion. Later I tried my hand at



But at the moment my activity are centered around microcontroller programming and soldering.



"Question
1: What is your
experience in robotics
engineering?"



In the future, I would like to study the topic of artificial intelligence and modeling and deepen my knowledge in IT



But AI is already a part of our everyday life - streaming services such as Netflix or Yandex.Music



My expirience in robotics started from my brother, he is a robot football coach. He told me a lot about robotics and I got interested.



The most familiar to me the field of industrial and special robotics as my specialty.

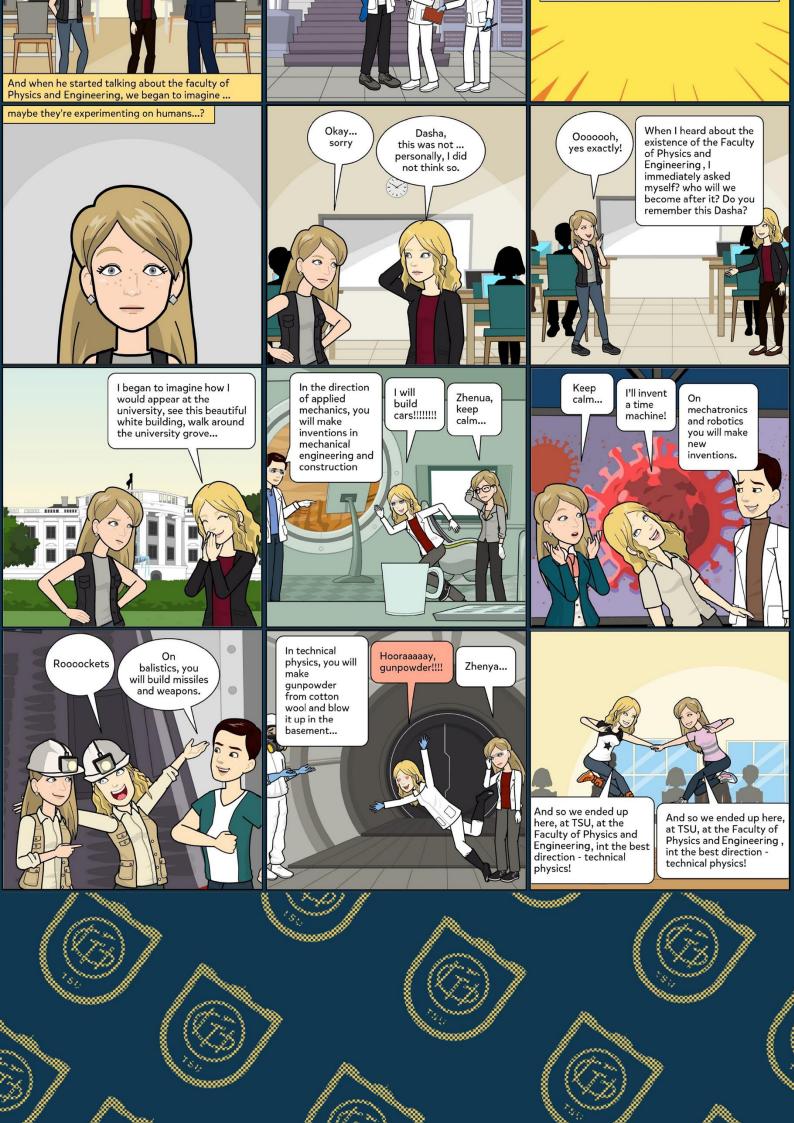




And about Al. I think it is one of the most challenging area for the moment. Al and machine

The most challenging area for me is everything about hard mathematical analysis. I find it difficult to work with

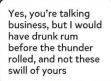




# VLAD PIRATE AND ROM SORCERER vs STORM Vlad Fedorov, Roman Sorokin



12 hours ago



1. Hello, Pirate! It would be a stout now, not sweating in the cabin



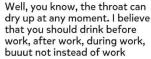


Of course I know, I gave the dog a try and he spit it out. I took it from a monkey on the island. We ate all the monkeys on the island, except for one, she was constantly screaming, something like "Legacy Warrior", well, she fought well, due to the fact that she could not be eaten. Then we took this monkey to our ship Why did you choose about strudel at all?

I wanted to make sure that you tried at least something delicious besides rum, bourbon, etc. You're holding a bottle in your hand even now...



I wanted to make sure that you tried at least something delicious besides rum, bourbon, etc. You're holding a bottle in your hand even



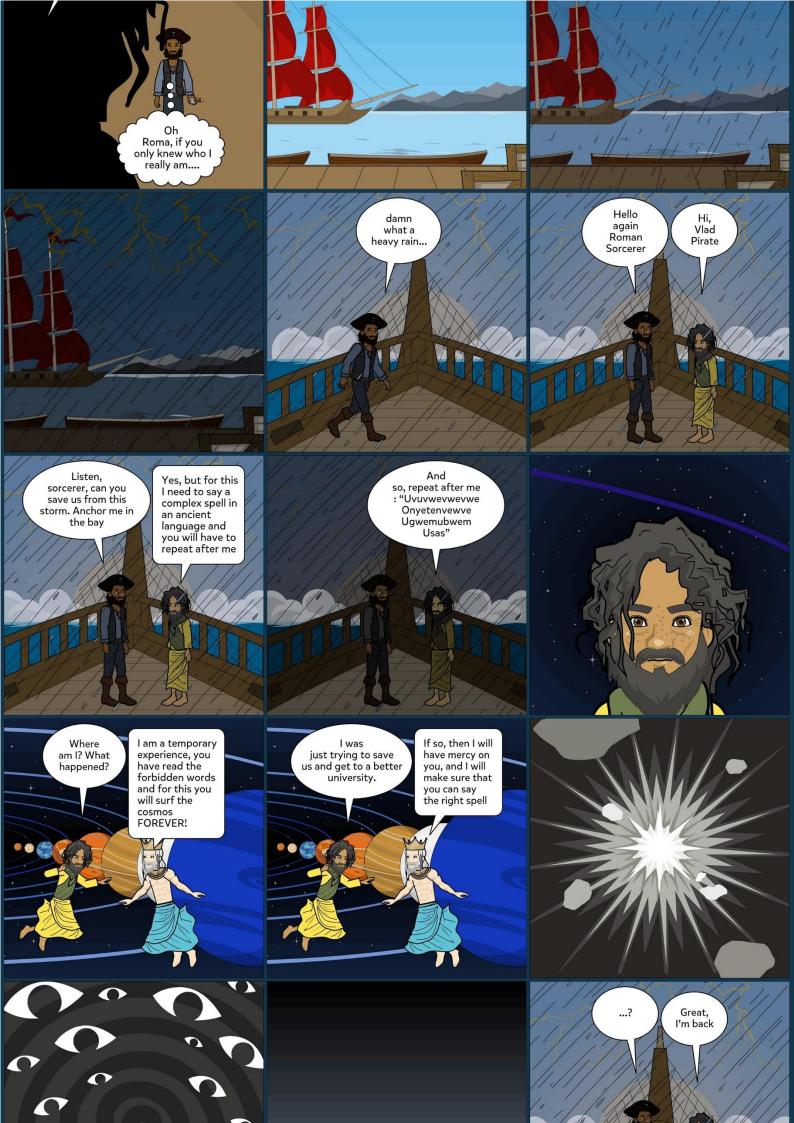


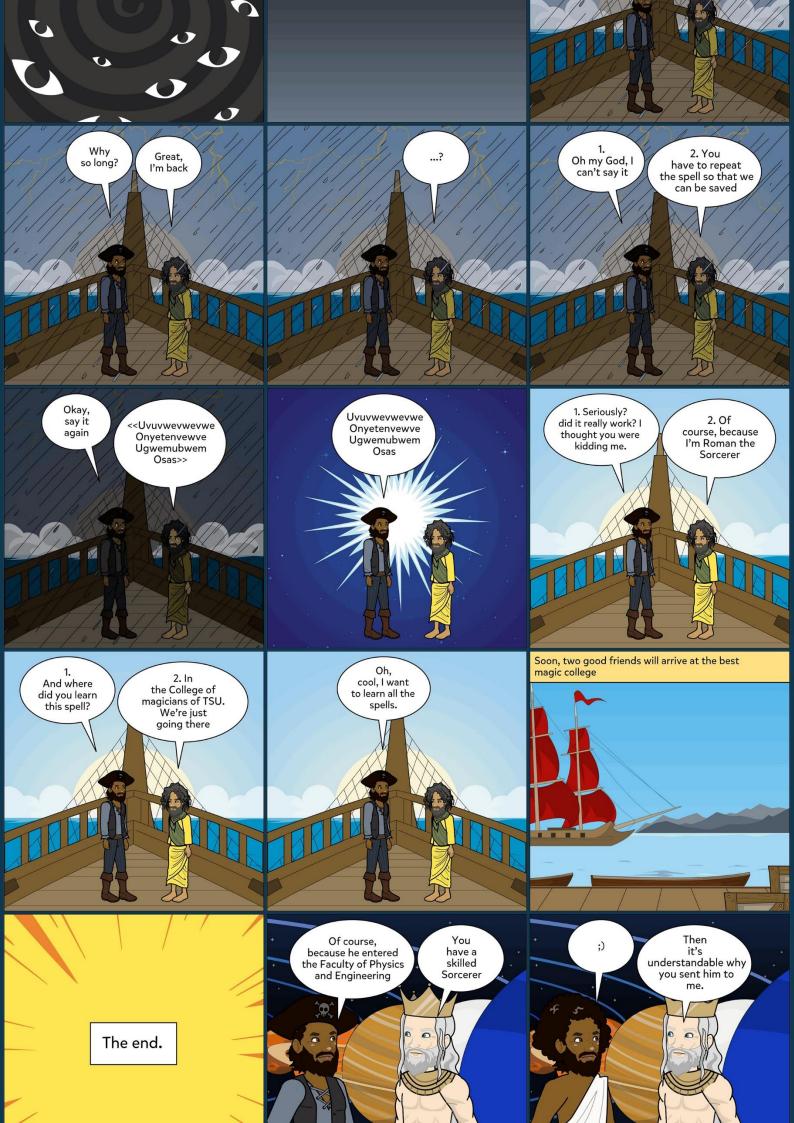
Vlad is a kringe, but I like) So what kind of job do you have?

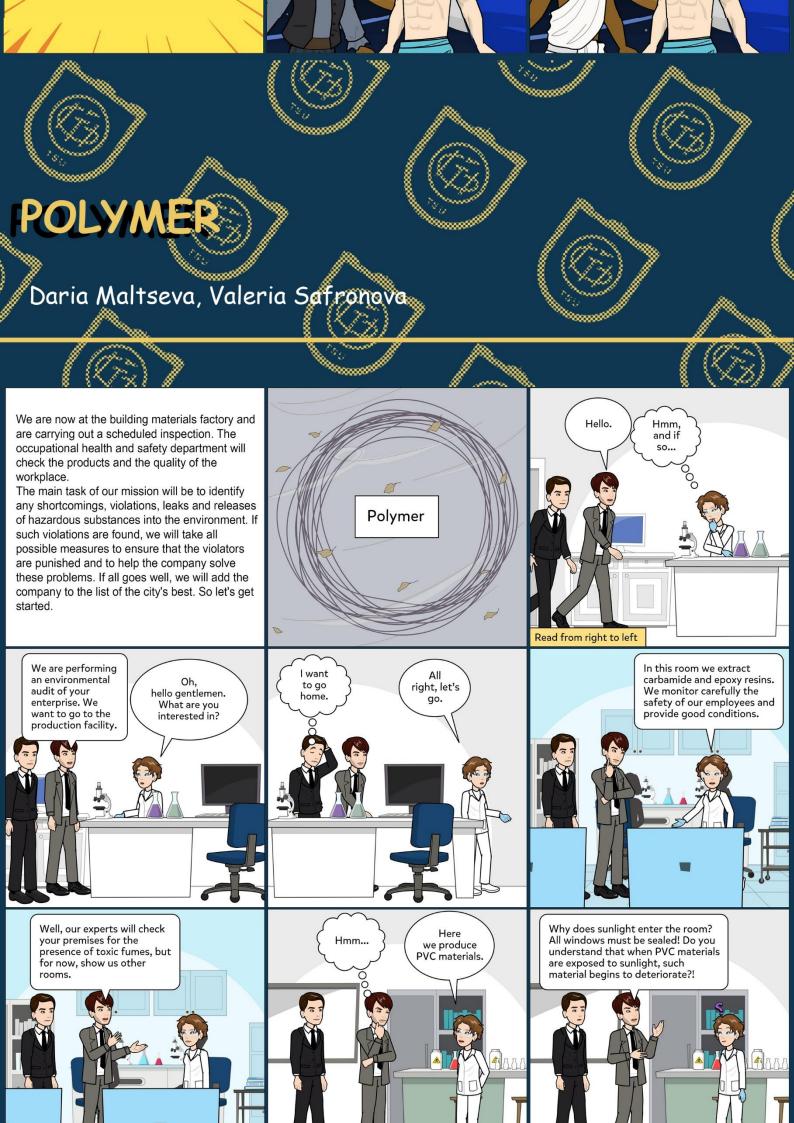


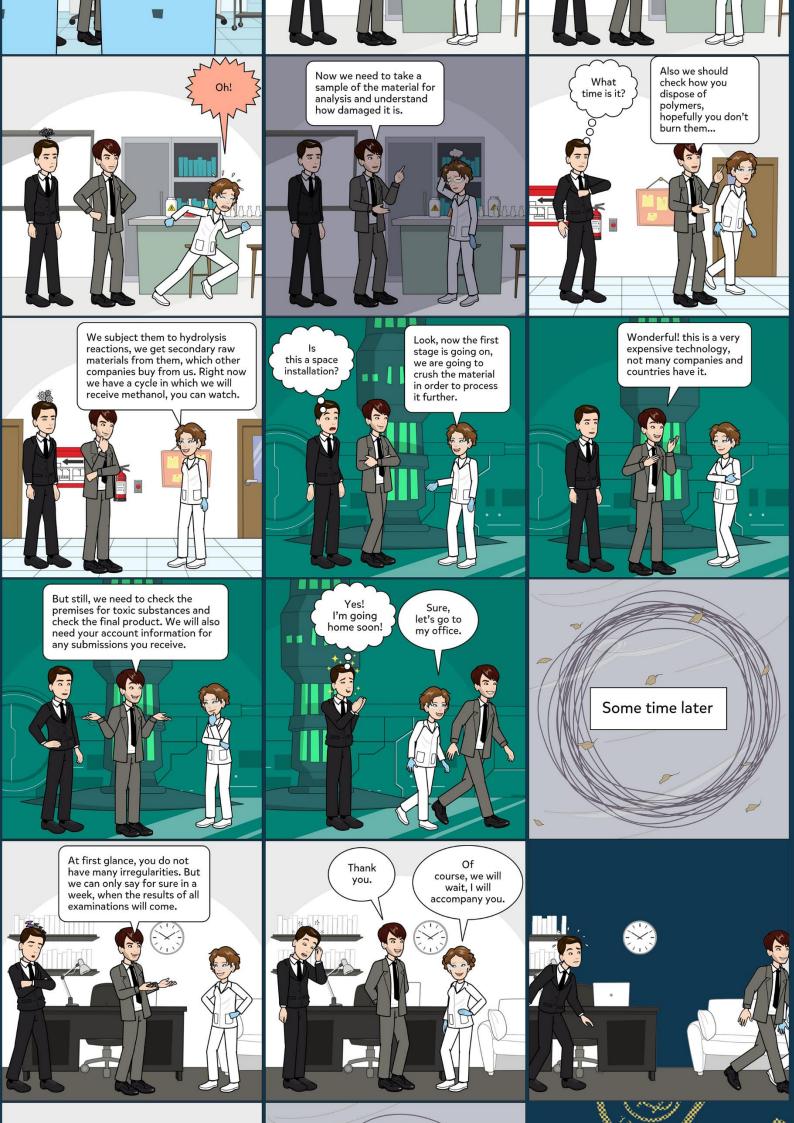




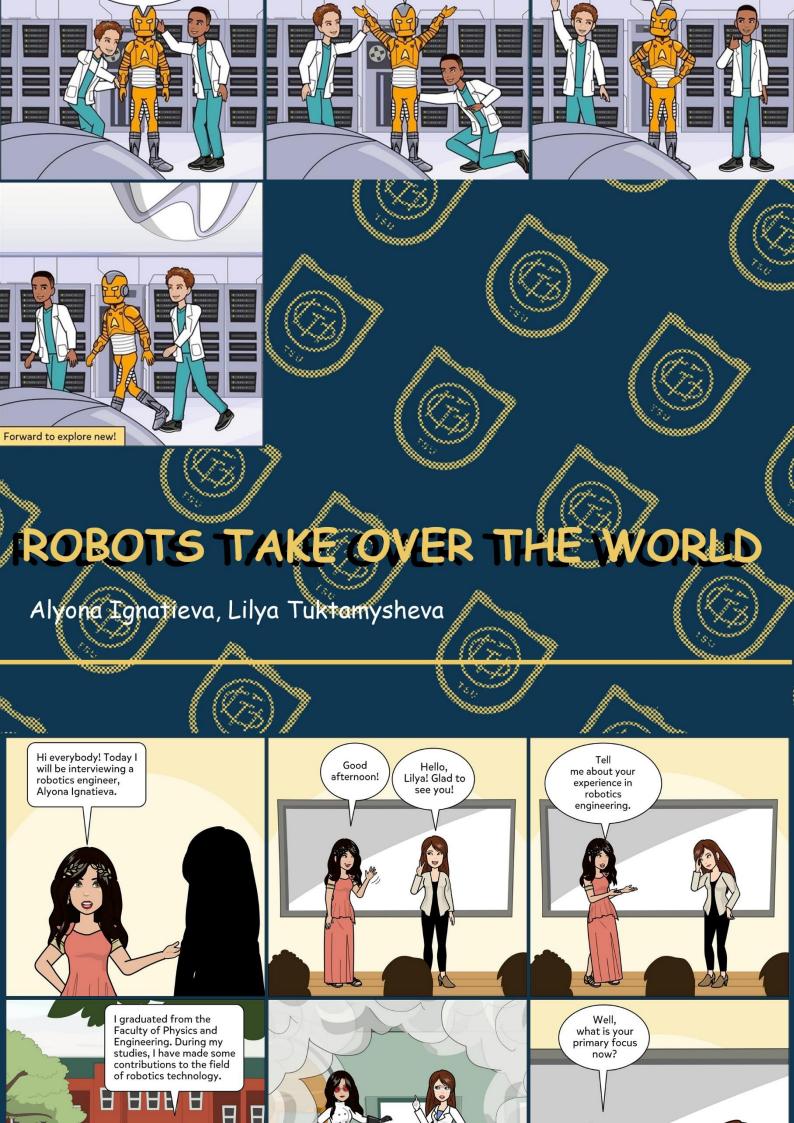


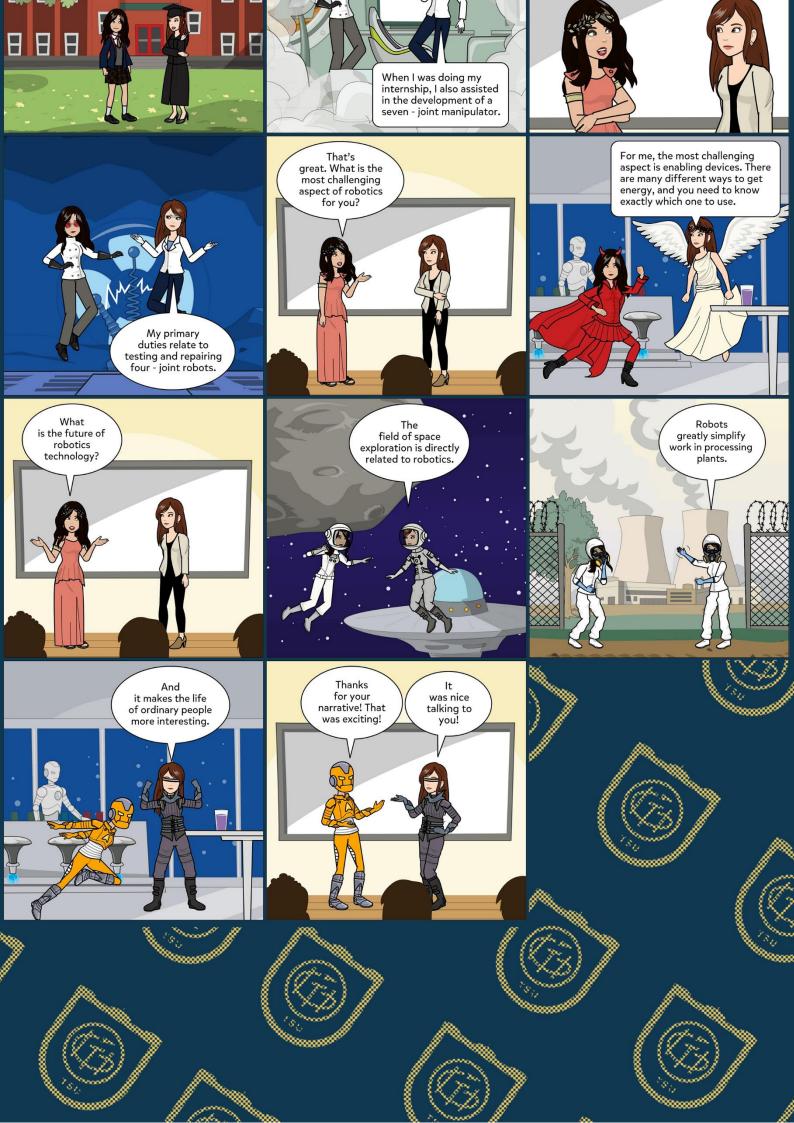












### REAL-LIFE ROBO

Ibrahim Alyousef, Rodion Galimulin, Elizar Chaykin

hello friends. let me first introduce our team, my name is Ibrahim and these are my friends Elizar and Radion.

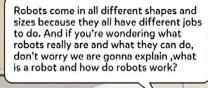


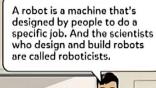
in today's lecture we are going to talk about Real-life robots that will make you think the future is now. So let's get started.



What do you picture in your mind when you think of robots? Do you think of a walking, talking piece of metal like this?

A lot of people do, because some robots really do look sort of like people. But despite what you see in the movies, most real-life robots don't look like us. They can look like animals, or like things you've never even seen before.





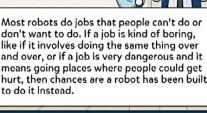


The very first robot was built over 50 years ago to help build cars in a factory.



Most robots do jobs that people can't do or don't want to do. If a job is kind of boring, like if it involves doing the same thing over and over, or if a job is very dangerous and it means going places where people could get hurt, then chances are a robot has been built

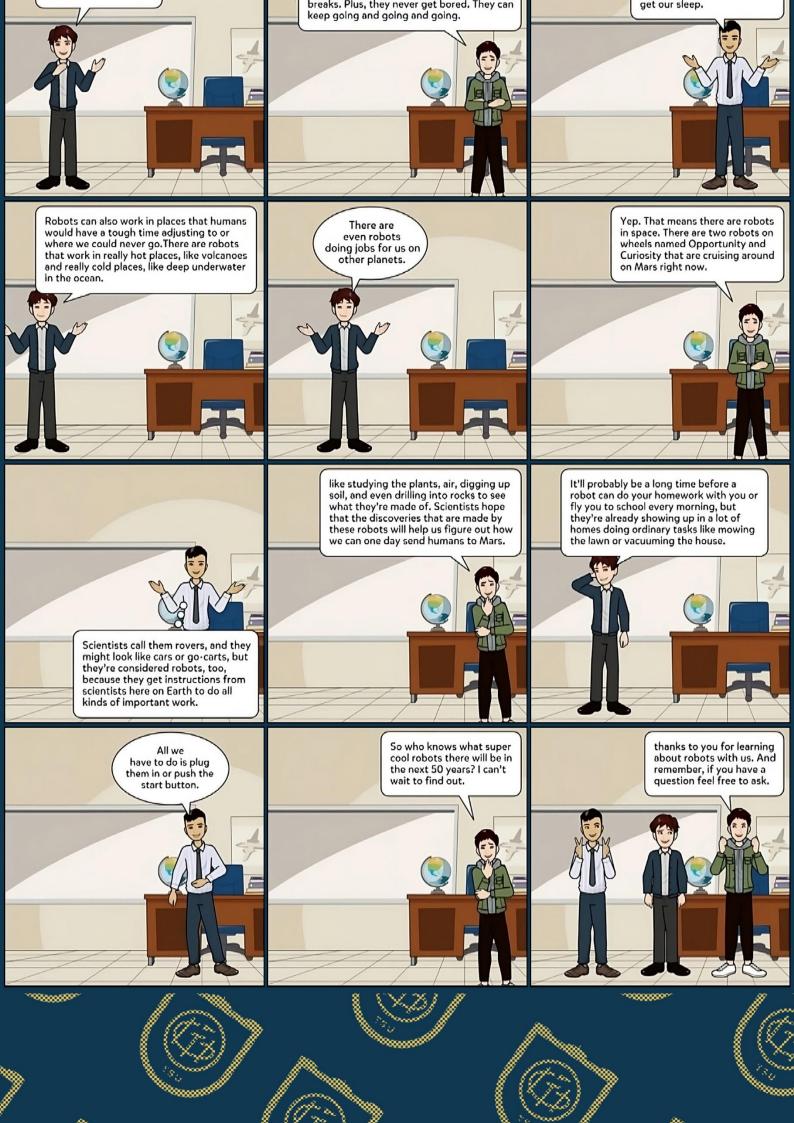
of other kinds of



And robots work in lots Robots are good at jobs like these because, unlike humans, they're less likely to make factory jobs, too, like mistakes when they're working, and they don't go on vacations or even take lunch building computers.

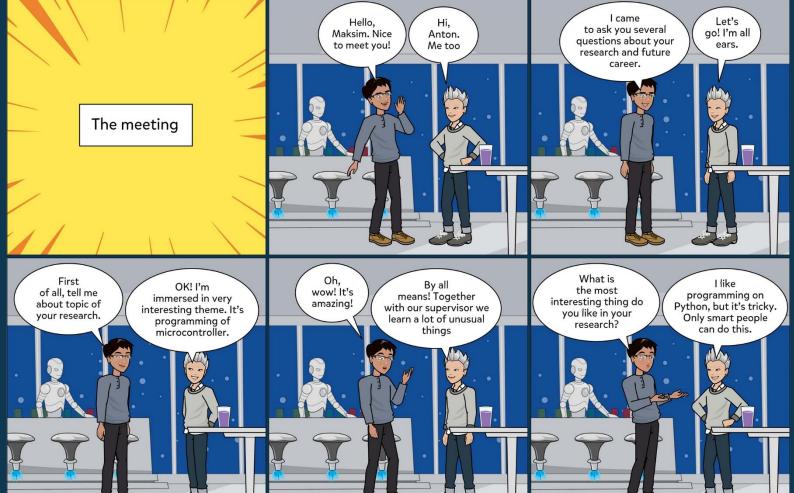


This makes night time jobs the perfect fit for bots. They can do things like control city, train after dark while we



#### MEETING OF TWO SUPERMINDS

Anton Kulikov and Maksim Tseytler



Sure, it's difficult. I was also interested in doing this.

Wow, cool! Talk to me your experience in robotics engineering. Well, I'm study a design features of automated and control systems. Main problem of automation and control relay to mechanical system, automatic perception, navigation and design making system.



That's a good idea! I have ro run, so let's meet to discuss next time.

That's sounds great.

Maybe we can do a cooperative

Bye

OK, I'll write you later. Bye





### INFLUENCE OF ROBOTS IN

Hung Nguyen



In the future, humans have been completely replaced by robots.Technology helps people not have to do anything even the smallest. Society now depends on machines, humans are just a secondary factor in it



He only knew the truth when his friend came to inform him



However, the machine gradually lost control and made society into chaos



Already knew the truth, he decided to go back in time to prevent himself from activating this technology though it helped him get money and fame











